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#### **SUMMARY**

Over 2 years' professional experience specializing in Six Sigma, Lean and Kaizen strategies for optimizing Industrial and automated processes. Motivated to work in an environment where I can contribute towards a goal and see things to completion.

#### **EDUCATION**

University of Texas at Arlington- Master of Science- Industrial Engineering- GPA 3.4 University of Mumbai- Bachelor of Engineering- Instrumentation and controls- GPA 3.5

May 2019

May 2016

### **SKILLS AND AREAS OF EXPERTISE**

**Industrial:** Lean Six Sigma, Cost Reduction, 5S, 5 Whys, Time Studies, Quality assurance and control, MRP, PFMEA, APQP, KAIZEN, PDCA, DOE, SPC, TPM, TQM, Root cause analysis, Fishbone analysis, Value stream mapping, Process improvement

Manufacturing: Instrument and system design, Advanced control system design, Process automation, Power electronics

Software: AutoCAD, SolidWorks, WITNESS, SAS, Simatic, MATLAB, Python, LabVIEW, Ladder logic programing

## **PROFESSIONAL EXPERIENCES**

### TRILOK CORPORATION- Production and controls engineer

Mumbai, India (Jun 2015 - Jun 2017)

- Led a team of automation, electrical and mechanical engineers for manufacturing a PLC-SCADA based **automated** de-aeration unit for **BPCL refinery (Govt. of India)**
- Produced Mechanical and P&ID drawings on AutoCAD for the dissolved oxygen removal process
- Executed quality improvement program by overseeing PFMEA, TQM and maintaining ISO quality standards
- Conducted time study of the manufacturing processes to reduce unnecessary movements and increase productivity by 15%
- Reduced manufacturing cost by minimizing defects and non-value adding activities by 12%
- Achieved 23% increase in efficiency of the batch process for deaerating water (for boiler feed) by successfully combining mechanical
  and electrical systems and fine tuning PID for Water heater, Flow, Temperature, Vacuum and Level control loops
- Instituted preventive maintenance schedule ensuring optimal equipment operation without downtime
- Performed FAT, SAT, on site commissioning and produced SOPs, user and maintenance manuals

# **VELORQ ELECTRIC KITS- Co-founder**

Mumbai, India (Jan 2016 - Jul 2017)

- Designed and built a DC motor based 'electric kit' for special needs and multi-utility bikes
- Reduced inventory cost of electric motors by 33% using demand-based (Pull) manufacturing technique like Just-in-time
- Optimized kit installation by preparing process charts and implementing Kaizen methodology
- Increased company **profits** by **12**% by incorporating **lean, continuous improvement and cost** control methods like eliminating waste, value stream mapping and project budgeting
- Increased process efficiency by 20% by simulating the manufacturing process on WITNESS
- Instituted Six sigma and improved quality by 26% and conducted failure mode and effect analysis of electric kits
- Performed troubleshooting and diagnostic tests of electronic components and mechanical tensioners ensuring 100% end user satisfaction

## **ACADEMIC PROJECTS**

## **OMRON LD autonomous robot**

2018-2019

- Worked on OMRON based service robots and development of 100 kg ROS based autonomous mobile robot (AMR)
- Collaborated with ROS programming team to enhance path planning, obstacle avoidance and optimize PID values for motor control
- Developed maps, configured SICK lasers and fail safe parameters on OMRON mobile planner software
- Programmed and interfaced Windows and Arduino for operating doors, lights, sound and controlling the robot remotely through Wi-Fi

# HYBRID ELECTRIC VEHICLE (HEV)- People's Choice Award (VJTI)

2015-2016

- Fabricated the concept of **Parallel Hybrid architecture** in a power scooter using a Brushless DC motor.
- Designed and constructed an **Electronic control unit (ECU)** for modulating throttle position using servo, actuation of clutch by taking feedback from wheel speed sensors (inductive) and signaling the Brushless DC motor controller.

## PERSONAL TRANSPORT VEHICLE (PTV)- 1st Prize (MUMBAI UNIVERSITY)

2014

- Designed and fabricated the chassis, MOSFET based motor drive, and micro controller based motor speed controller.
- Developed and built a compact, portable electric vehicle that can be used for personal commute.